

The role of maps as a major enabler towards automated driving

## 5 myths about maps and map making...

- 1. Maps are not needed for Autonomous Driving
- 2. Maps can easily be made by using sensors only
- 3. Car OEMs will not give map makers access to car sensor data
- 4. Map freshness cannot be delivered with the required high quality in a scalable and efficient way
- 5. Market leaders in ADAS are automatically the future market leaders of maps for Autonomous Driving



## Historic evolution of using maps in the car



## Impact of "future trends" on map

The Internet of Things and Automated Driving create

#### **More Demand** for maps

loT





#### Shift of map domain

AD







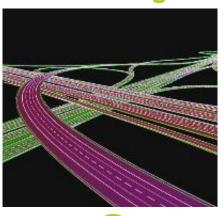


## The role of a map in automated driving

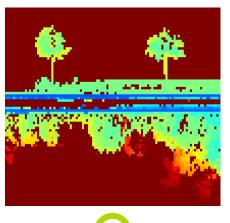
**Navigation** 



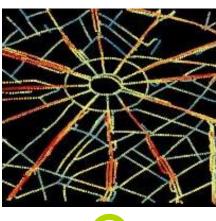
**Planning** 



Localization



**Comfort** 



Getting from A to B

Planning the next maneuver within and beyond sensor horizon

Complement sensors in positioning

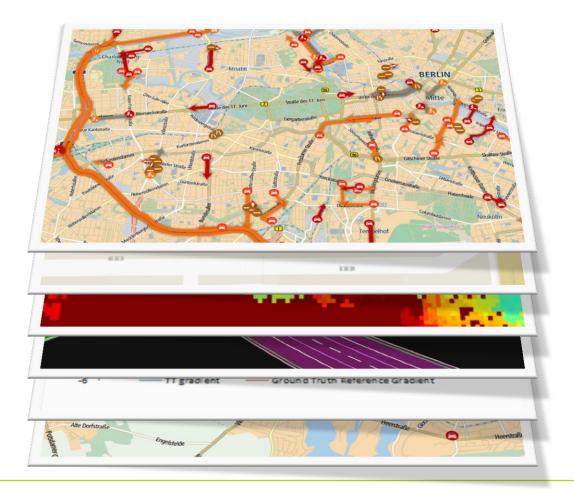
Making automated driving feel comfortable



## What is a map?

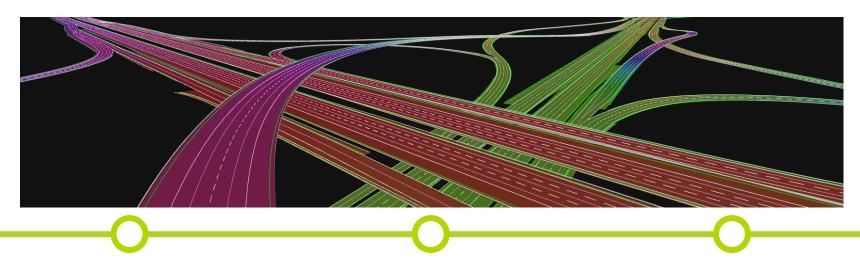
#### Several map layers

- Live map layers
- Real-time map updates
- Localization content
- HD Map
- ADAS content
- Navigation map





## **Advanced Map for Automated Driving**



#### **Highly Detailed**

3D Lane Geometry

- markings
- centerlines
- road boundaries

### **Highly Accurate**

Sub-meter absolute
Decimeter-level relative

#### **Richly Attributed**

Lane-level attributes

- speed restrictions
- divider markings

Position Landmarks
RoadDNA



## RoadDNA provides robust & scalable positioning content



#### **Robust**

Tolerant regarding changes in reality or map version

#### Scalable

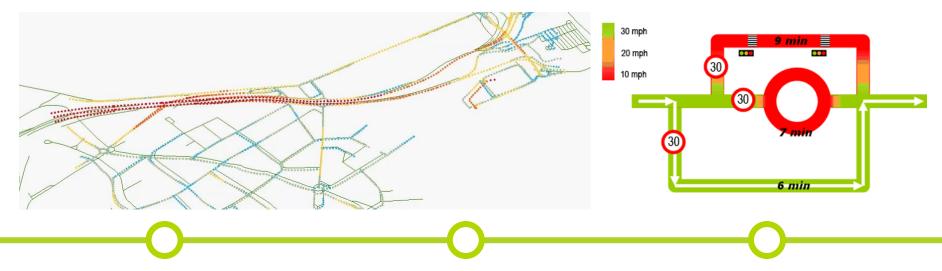
Low storage
Low processing
Automated production

#### Highly accurate

<0.5 m longitudinal & <0.15m lateral accuracy



## **Driver behavioral data – Local Speeds (IQ Routes 2.0)**



#### Big data

Pattern data mining of vehicle probes allows creation of predictive map layers

#### Scalable

Vehicle probe data is similar around the world

#### **Comfort**

These layers allow the automated car to drive in an intelligent human way



#### This is not fiction...







Germany ~28,000 km

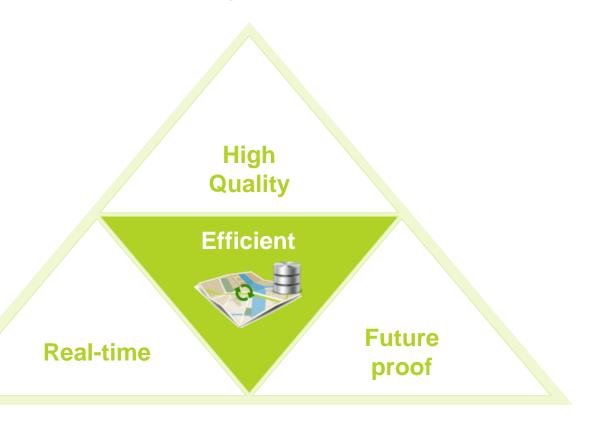
US: CA, MI + NV ~41,000 km

Roadmap EUR and NAM



## **Essential components of a mapmaking platform**

- Highly Accurate
- Detailed
- Feature rich
- Up-to-date
- Prepared to support new layers
- Scalable





#### PROFESSIONAL MAPMAKING

Mobile Mapping Vans Field Survey Authoritative Sources







#### **COMMUNITY INPUT**

Probe Data

Active Community Input









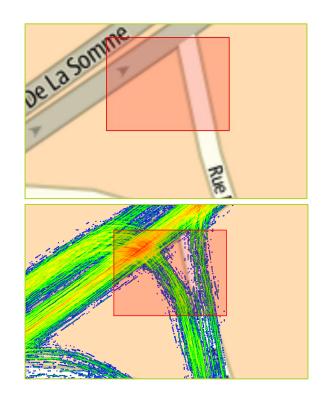
#### **INTELLIGENT MAPMAKING**

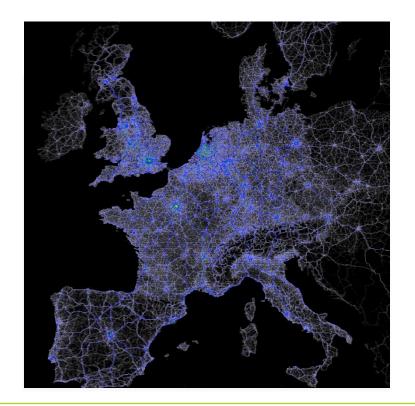
Perfected approach that combines professional mapmaking methods with community input.





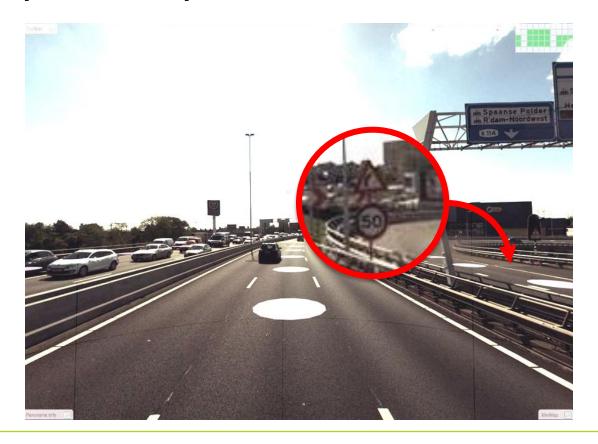
## Intelligent map making in action





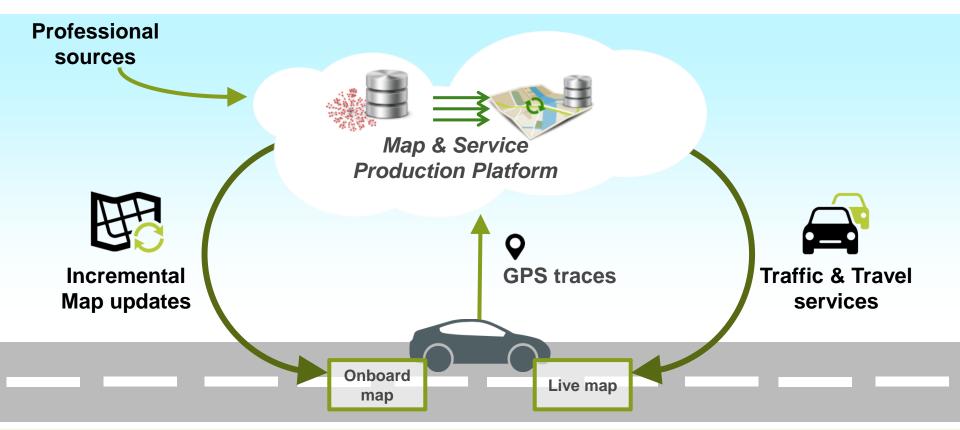


## Mapping expertise on top of sensor data and machine learning





## Real-time maps and Traffic and Travel services



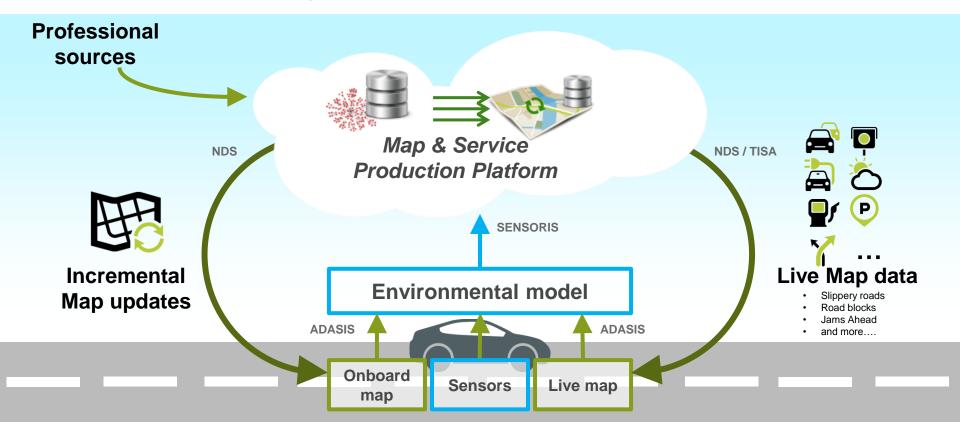


## One day of community input





## Automated Driving requires an environmental model



# 5 mgg kgut nats no making...

- 1. Maps are needed for Autonomous Driving
- 2. Maps cannot easily be made by using sensors only
- 3. Car OEMs will share sensor data if it makes sense and does not impact users
- 4. Map freshness can be delivered with the required high quality in a scalable and efficient way
- 5. Market leaders in ADAS are not automatically the future market leaders of maps for Autonomous Driving

## THANK YOU

ANY QUESTIONS?

