



Automated Driving Applications and Technologies for Intelligent Vehicles

Anna Schieben

Do we still need to consider Human Factors? -The challenges regarding human-vehicle interactions for automated vehicles

Technical Workshop

Athens, Greece 21-22 APRIL 2016



//Overview

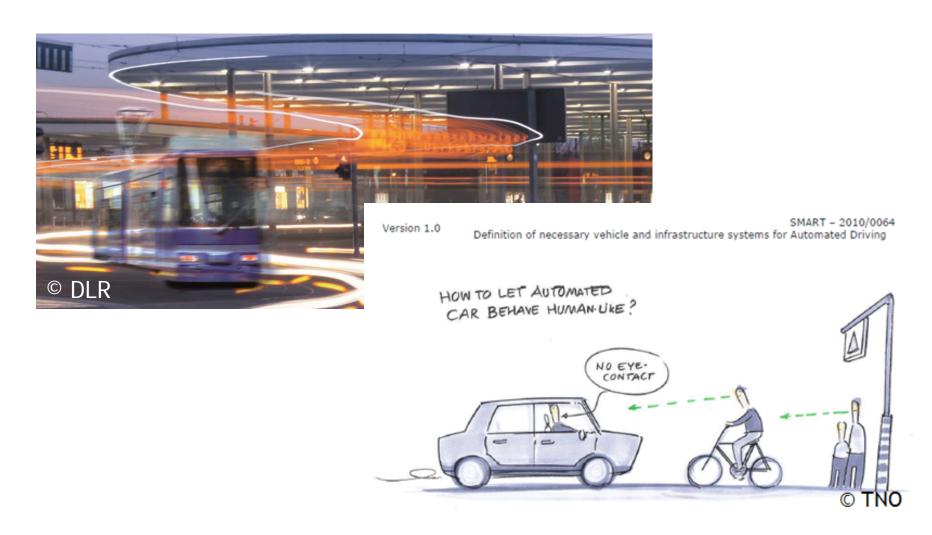
- How automation will change the human-vehicle interaction
- Do we still need to consider Human Factors?
- Challenges regarding the design of human-vehicle interaction for automated vehicles
 - Examples from EU projects AdaptIVe, HOLIDES, Citymobil2 and national projects
- Conclusions



// Automated and connected driving - Changes in the role of the driver



// Automated and connected driving - Changes in the interaction with other traffic participants





// Do we still need to consider Human Factors?

YES - but why?

- Automated vehicles are to be implemented in mixed traffic environments where humans play a central role:
 - as drivers or passengers
 - as other road users (vehicle drivers or VRUs)
 - as operators
- → Automation does not remove the human it changes the way humans interact with vehicles
- "[...] the irony that one is not by automating necessarily removing the difficulties, and also the possibility that resolving them will require even greater technological ingenuity than does classic automation."
 (Bainbridge, 1983)



// Do we still need to consider Human Factors?

- Human Factors can help:
 - to detect major effects of automated vehicles on human performance:
 - (short-& longterm) automation effects and implications for drivers
 - Driver workload, distraction, situation awareness
 - Trust, acceptance, fears, disuse and misuse
 - Performance and loss of skills
 - Differences in driver populations (e.g. age, intercultural aspects, experts - beginners - professional drivers)
 - (short-& longterm) automation effects and implications for other traffic participants
 - Trust, acceptance, fears
 - Information needs for safe interaction



// Do we still need to consider Human Factors?

- Human Factors can help:
 - to improve the interaction design for human vehicle interaction e.g.
 - Design of HMI and selection appropriate information and communication channels
 - Design of transitions of control
 - Selection of appropriate non-related driving tasks & definition of misuse
 - Design of automation behaviour
 - to design instruction strategies and trainings procedures
 - to define guidelines, rules and standards for HMI design



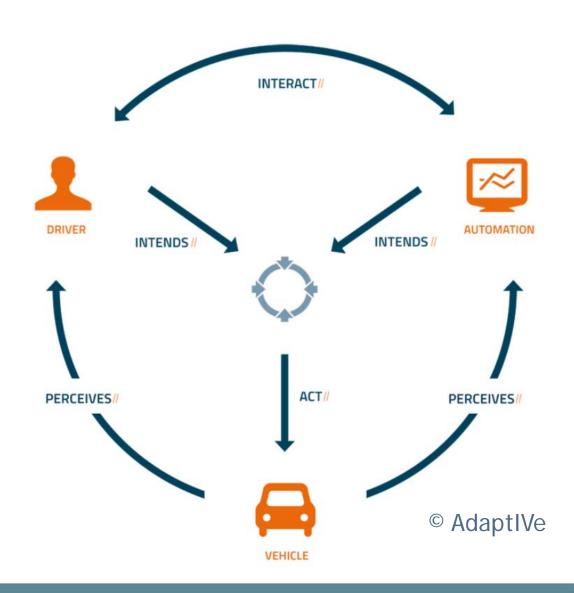
// Definition of the automation levels

SAE level	Name	Narrative Definition	Execution of Steering and Acceleration/ Deceleration	Monitoring of Driving Environment	Fallback Performance of <i>Dynamic</i> <i>Driving Task</i>	System Capability (Driving Modes)
Human driver monitors the driving environment						
0	No Automation	the full-time performance by the <i>human driver</i> of all aspects of the <i>dynamic driving task</i> , even when enhanced by warning or intervention systems	Human driver	Human driver	Human driver	n/a
1	Driver Assistance	the driving mode-specific execution by a driver assistance system of either steering or acceleration/deceleration using information about the driving environment and with the expectation that the human driver perform all remaining aspects of the dynamic driving task	Human driver and system	Human driver	Human driver	Some driving modes
2	Partial Automation	the driving mode-specific execution by one or more driver assistance systems of both steering and acceleration/deceleration using information about the driving environment and with the expectation that the human driver perform all remaining aspects of the dynamic driving task	System	Human driver	Human driver	Some driving modes
Auton	Automated driving system ("system") monitors the driving environment					
3	Conditional Automation	the <i>driving mode</i> -specific performance by an <i>automated</i> driving system of all aspects of the dynamic driving task with the expectation that the <i>human driver</i> will respond appropriately to a request to intervene	System	System	Human driver	Some driving modes
4	High Automation	the driving mode-specific performance by an automated driving system of all aspects of the dynamic driving task, even if a human driver does not respond appropriately to a request to intervene	System	System	System	Some driving modes
5	Full Automation	the full-time performance by an automated driving system of all aspects of the dynamic driving task under all roadway and environmental conditions that can be managed by a human driver	System	System	System	All driving modes

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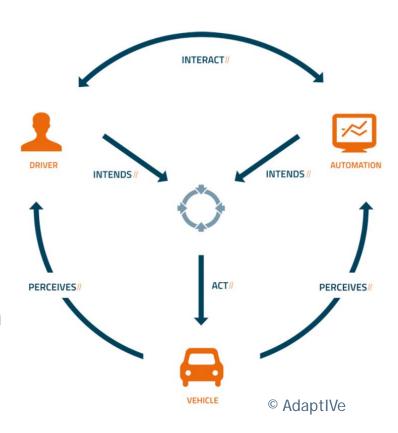


// Driver - vehicle interaction



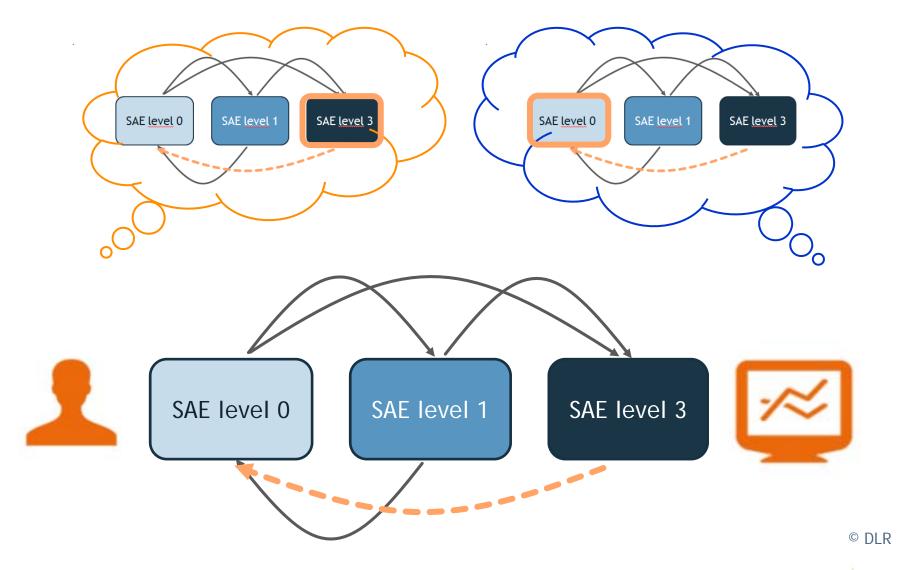
// Driver - vehicle interaction

- Examples for relevant interaction design issues:
 - Transitions of control between different levels of automation
 - Design for reasonable usage and avoidance of misuse
 - Adaptation of automation behaviour on driver state and driving style/driver preference





// Driver - vehicle interaction: Transitions of control





//Driver - vehicle interaction: Transition of control

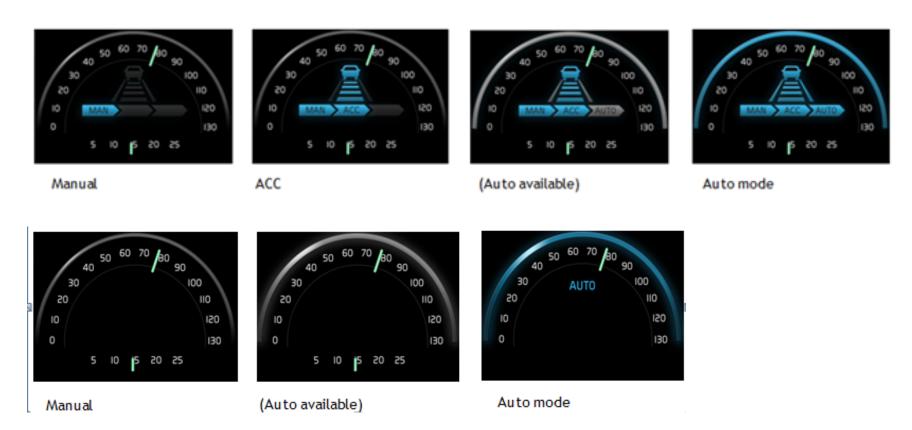
- Risk of "control vacuum" or "control surplus"
- Challenges for the interaction design:
 - Transitions need to be safe
 - Operation faults need to be avoided
 - Mode confusion should be avoided by presention explicit information about available and activated automation level



//Driver - vehicle interaction: Transition of control



Experimental evaluation of HMI design variants for the instrument cluster at VTEC



//Driver - vehicle interaction: Transition of control



 Concept for integrating information of divers driver assistance systems and automation levels in a holistic concept at DLR





// Design of reasonable usage/avoidance of misuse



- Challenges for the interaction design:
 - Take-over capability of the driver needs to be ensured, while allowing the driver to engage in non-driving related tasks
 - Misuse needs to be avoided
- Concept for integrating personal mobile devices in the overall vehicle system -> DLR project MOBIFAS

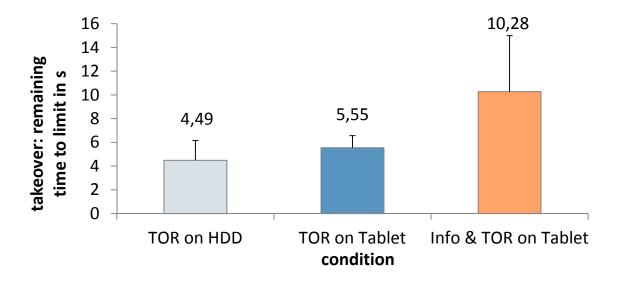




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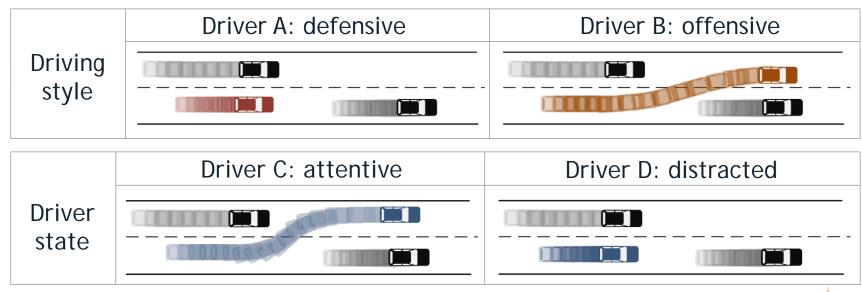




// Adaptation of automation behaviour



- Challenges for the interaction design:
 - Ensure comforable driving
 - Support the driver in an optimal way
- Concept for adapting the automation behaviour with respect to driver preferrence/driving style and driver status

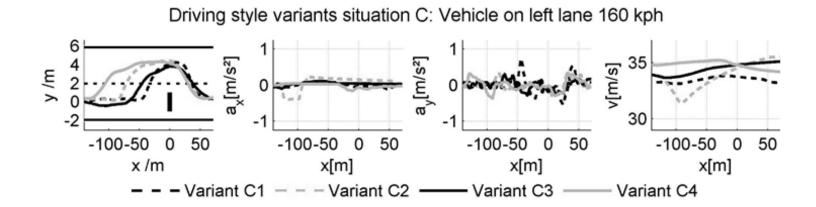




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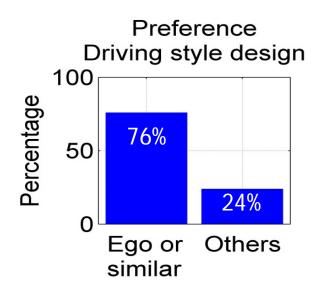




// Adaptation of automation behaviour



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//Interaction with other traffic participants

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// Interaction with other traffic participants

- Automated vehicles are to be implemented in mixed traffic environments where humans plays a central rule as other road users
 - Drivers of other vehicles
 - Vulnerable Road Users (VRUs)
- Various forms of interaction between drivers of conventional vehicles and other traffic participants
 - Eye contact, hand signals, gestures
- Challenges for the interaction design:
 - Safe and intuitive interaction with other traffic participants
 - Implicit and explicit communication
 - Human-like behaviour?





//Interaction with other traffic participants



- Focus groups, interviews, online survey by IST Leeds and DLR:
- Which kind of behaviour and interaction do people expect from driverless vehicles in shared environments?
- 99% of the participants expect that vehicles behave according to traffic rules
- About 50% would like to have additional visual and acoustic information about
 - Direction of movement
 - Detection of objects in the near field
 - Planned/next actions of the vehicle



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// Conclusions

- Automation per se does not decrease Human Factors research needs
- The human stays a crucial part in the overall human vehicle system
- Several Human Factors effects of automated vehicles have not been (fully) explored yet
- Vehicle automation will technically further develop interaction design needs to keep pace
- Standardization of generic interaction concepts (not OEM specific HMI solutions) would help to significantly reduce critical interaction





//Interested in further information? - References

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